University of Bahrain Department of Mathematics MATHS311: Abstract Algebra 1 Fall 2017 Dr. Abdulla Eid



## **Project 2: Dihedral Groups**

The aim of this project is to provide further practice in:

- 1. Rigid Motion
- 2. Group of Symmetries
- 3. Dihedral Groups
- 4. Representation of a group

A **symmetry** of a geometric figure is a rearrangement of the figure preserving the arrangement of its sides and vertices as well as its distances and angles. A map from the plane to itself preserving the symmetry of an object is called a **rigid motion**.

We have seen the group of symmetries of the square  $D_4$  in class. Anagously we can define the *n*th **dihedral group**  $D_n$  to be the group of all rigid motions of the plane of regular *n*–gon. The group  $D_n$  consists of rotations and reflections.

1. What is the group of symmetries of an equilateral triangle  $D_3$ ? (Describe the elements as well as the Cayley's table)

(Hint:  $D_3$  is the symmetry group of the Mercedes–Benz logo)

- 2. What is the size of  $D_n$ ? (Hint: How many choices we can replace the first vertex? If the first vertex is fixed, how many choices we have for the second one? Try = 3,4,5 to get an idea).
- 3. How many different rotations in  $D_n$ ?
- 4. Show that the subgroup of all rotations  $R_n$  is a cyclic group generated by a rotation r. What is the order of the rotation subgroup?

- 5. Show that any reflection has order 2.
- 6. Let *s* be the reflection that fixes vertex 1. Show that  $srs = r^{-1}$ . conclude that  $D_n$  is nonabelian group.
- 7. Show that  $R_n$  is a normal subgroup of  $D_n$  and that  $D_n/R_n$  is a group of order 2.
- 8. Show that  $D_n$  is generated by the elements r, s subject to the conditions  $r^n = e, s^2 = e, srs = r^{-1}$ .

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