

# Section 4.3

## Linear Independent Vectors

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MATHS 211: Linear Algebra

## Goal:

- 1 Define Linearly independent and linearly dependent.
- 2 From dependent to independent.
- 3
- 4

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# Subspace

## Definition 1

Let  $V$  be a vector space.  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$  are called **linearly independent vectors** if the equation

$$k_1\mathbf{v}_1 + k_2\mathbf{v}_2 + \dots + k_n\mathbf{v}_n = \mathbf{0}$$

has only the unique solution  $k_1 = 0, k_2 = 0, \dots, k_n = 0$  (called the **trivial solution**).

Note: This means  $k_1, k_2, \dots, k_n$  are forced to be zero.

## Definition 2

Let  $V$  be a vector space.  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n$  are called **linearly dependent vectors** if the equation

$$k_1\mathbf{v}_1 + k_2\mathbf{v}_2 + \dots + k_n\mathbf{v}_n = \mathbf{0}$$

has other solution than  $k_1 = 0, k_2 = 0, \dots, k_n = 0$  (called the **nontrivial solution**).

### Example 3

Determine whether the vectors  $e_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ ,  $e_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ ,  $e_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$  are linearly independent in  $\mathbb{R}^3$  or not.

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### Example 4

Determine whether the vectors  $\mathbf{v}_1 = \begin{pmatrix} 1 \\ -2 \\ 3 \end{pmatrix}$ ,  $\mathbf{v}_2 = \begin{pmatrix} 5 \\ 6 \\ -1 \end{pmatrix}$ ,  $\mathbf{v}_3 = \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$  are linearly independent in  $\mathbb{R}^3$  or not.

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### Example 5

Determine whether the vectors  $\mathbf{v}_1 = \begin{pmatrix} 1 \\ 2 \\ 2 \\ -1 \end{pmatrix}$ ,  $\mathbf{v}_2 = \begin{pmatrix} 4 \\ 9 \\ 9 \\ -4 \end{pmatrix}$ ,  $\mathbf{v}_3 = \begin{pmatrix} 5 \\ 8 \\ 9 \\ -5 \end{pmatrix}$

are linearly independent in  $\mathbb{R}^4$  or not.

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### Example 6

Determine whether the vectors  $P_1 = 1$ ,  $P_2 = X$ ,  $P_3 = X^2$ ,  $\dots$ ,  $P_n = X^n$  are linearly independent in  $\mathbb{P}_n$  or not.

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### Example 7

Determine whether the vectors  $P_1 = 1 - X$ ,  $P_2 = 5 + 3X - 2X^2$ ,  $P_3 = 1 + 3X - X^2$  are linearly independent in  $\mathbb{P}_2$  or not.

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## Theorem 8

*The set  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  is linearly independent if and only if at least one of the vector is expressible as linear combination of the rest.*

## Corollary 9

*Let  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  be a linearly dependent set with  $\mathbf{v}_1 = k_2\mathbf{v}_2 + \dots + k_n\mathbf{v}_n$ , then*

$$\text{span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\} = \text{span}\{\mathbf{v}_2, \mathbf{v}_3, \dots, \mathbf{v}_n\}$$

## Example 10

Determine whether the vectors  $\mathbf{v}_1 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ ,  $\mathbf{v}_2 = \begin{pmatrix} 2 \\ 4 \\ 6 \end{pmatrix}$ ,  $\mathbf{v}_3 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$ ,

$\mathbf{v}_4 = \begin{pmatrix} 1 \\ 4 \\ 5 \end{pmatrix}$  are linearly independent in  $\mathbb{R}^3$  or not. If not, find an

independent set from these vectors that gives the same span.

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## Theorem 11

*The set  $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$  of vectors in  $\mathbb{R}^n$  with  $r > n$  is linearly dependent.*

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## Theorem 12

- 1 A set containing  $\mathbf{0}$  is linearly dependent.
- 2 A set with exactly one vector is linearly independent if and only if that vector is not  $\mathbf{0}$ .
- 3 A set with exactly two vectors if and only if neither vector is a scalar multiple of the other.

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# Maps( $\mathbb{R}, \mathbb{R}$ )

## Definition 13

Let  $f_1, f_2, \dots, f_n$  are functions that are  $(n - 1)$  differentiable functions. The determinant

$$W_{f_1, f_2, \dots, f_n}(x) := \det \begin{pmatrix} f_1(x) & f_2(x) & \dots & f_n(x) \\ f_1'(x) & f_2'(x) & \dots & f_n'(x) \\ f_1''(x) & f_2''(x) & \dots & f_n''(x) \\ \cdot & \cdot & \dots & \cdot \\ \cdot & \cdot & \dots & \cdot \\ \cdot & \cdot & \dots & \cdot \\ f_1^{n-1}(x) & f_2^{n-1}(x) & \dots & f_n^{n-1}(x) \end{pmatrix}$$

is called the **Wronskian** of  $f_1, f_2, \dots, f_n$ .

### Theorem 14

If  $f_1, f_2, \dots, f_n$  have  $n - 1$  continuous derivatives with a **nonzero Wronskian**, then these functions are linearly independent.

### Example 15

Determine whether the vectors  $f_1 = 6$ ,  $f_2 = 4 \sin^2 x$ ,  $f_3 = 3 \cos^2 x$  are linearly independent in  $\text{Maps}(\mathbb{R}, \mathbb{R})$  or not.

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### Example 16

Determine whether the vectors  $f_1 = x$ ,  $f_2 = e^x$ ,  $f_3 = e^{-x}$  are linearly independent in  $\text{Maps}(\mathbb{R}, \mathbb{R})$  or not.

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