# Section 2.3 Determinant of a matrix

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MATHS 211: Linear Algebra

#### Goal:

- It define the determinant of a matrix.
- To find the determinant of a matrix using cofactor expansion (Section 2.1).
- **③** To find the determinant of a matrix using row reduction (Section 2.2).
- Explore the properties of the determinant and its relation to the inverse. (Section 2.3)
- To solve linear system using the Cramer's rule. (Section 2.3)
- The equation  $A\mathbf{x} = \mathbf{b}$  (Section 2.3)

## Properties of the determinant



• If  $det(A) \neq 0$ , then A has an inverse (invertible)

### Assume A is $5 \times 5$ matrix for which det(A) = -3 Find the following:









• det
$$((2A)^{-1})$$

Use determinant to decide whether the given matrix is invertible or not

$$A = \begin{pmatrix} 2 & 0 & -1 \\ 0 & 2 & 3 \\ -1 & 0 & 5 \end{pmatrix}$$

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Find the value(s) of k for which A is invertible.

$$A = \begin{pmatrix} 3 & k \\ k & 3 \end{pmatrix}, \qquad A = \begin{pmatrix} 2 & 1 & 0 \\ k & 2 & k \\ 2 & 4 & 2 \end{pmatrix}$$

Solution:

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## Adjoint matrix

#### Definition 4

Let  $A \in Mat(n, n, \mathbb{R})$  and  $C_{ij}$  is the cofacotr of  $a_{ij}$ , then the matrix with entries  $(C_{ij})$  is called the **matrix of cofactors from** A. The transpose of this matrix is called the **adjoint** of A and is denoted by adj(A).

#### Example 5

Use the adjoint method to find the inverse (if exists) to the following matrices:

$$A = \begin{pmatrix} -2 & 4 & 3\\ 1 & 2 & 0\\ 2 & -1 & -2 \end{pmatrix}$$

#### Theorem 6

$$A^{-1} = \frac{1}{\det(A)} \mathrm{adj}(A)$$

## Example 7

Use the adjoint method to find the inverse (if exists) to the following matrices:

$$A = \begin{pmatrix} -2 & 4 & 3\\ 1 & 2 & 0\\ 2 & -1 & -2 \end{pmatrix}$$

Use the adjoint method to find the inverse (if exists) to the following matrices:

$$A = \begin{pmatrix} 3 & 0 & 0 \\ -2 & 1 & 0 \\ 4 & 3 & 2 \end{pmatrix}$$

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Use the adjoint method to find the inverse (if exists) to the following matrices:

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos\theta & -\sin\theta \\ 0 & \sin\theta & \cos\theta \end{pmatrix}$$

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## Cramer's Rule

#### Theorem 10

If  $A\mathbf{x} = \mathbf{b}$  is a system of *n* linear equations in *n* unknowns such that  $det(A) = \neq 0$ , then the system has a unique solution given by

$$x_1 = \frac{\det(A_1)}{\det(A)}, x_2 = \frac{\det(A_2)}{\det(A)}, \dots x_n = \frac{\det(A_n)}{\det(A)},$$

where  $A_j$  is the matrix obtained by replacing the entries in the *j*th column of A by the entries in the matrix

$$\mathbf{p} = \begin{pmatrix} b_1 \\ b_2 \\ \cdot \\ \cdot \\ \cdot \\ \cdot \\ b_n \end{pmatrix}$$

#### Solve using Cramer's rule the following system of linear equations

 $3x_1 + x_2 = 2$  $4x_1 + x_2 = 3$ 

Solve using Cramer's rule the following system of linear equations

 $3x_1 + 5x_2 = 7$   $6x_1 + 2x_2 + 4x_3 = 10$  $-x_1 + 4x_2 - 3x_3 = 0$ 

The equation  $A\mathbf{x} = \mathbf{b}$ 

#### Theorem 13

The following are equivalent:

- A is invertible.
- $each det(A) \neq 0.$
- The reduced row echelon form is I<sub>n</sub>.
- $A\mathbf{x} = \mathbf{b}$  is consistent for every  $n \times 1$  matrix  $\mathbf{b}$ .
- **5**  $A\mathbf{x} = \mathbf{b}$  has a unique solution for every  $n \times 1$  matrix  $\mathbf{b}$ .